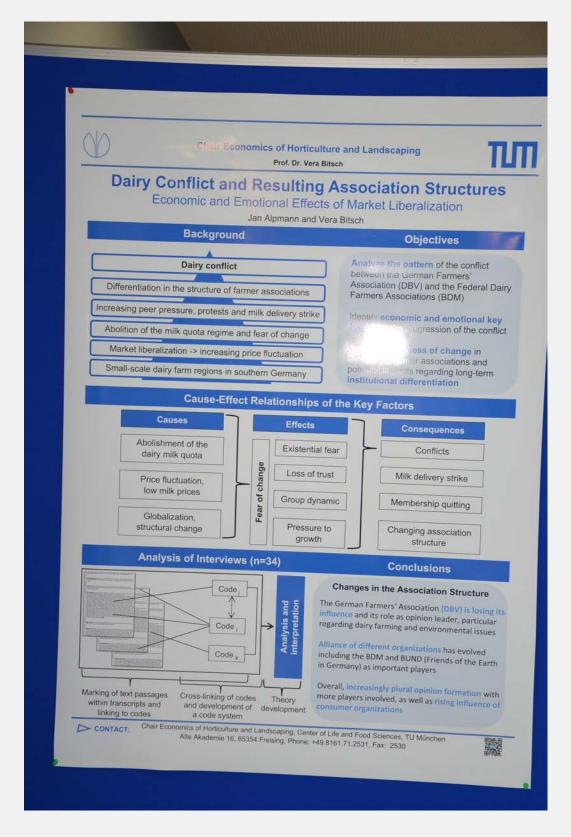
1stHEZagrar PhD Symposium [April 21, 2015]

Poster session



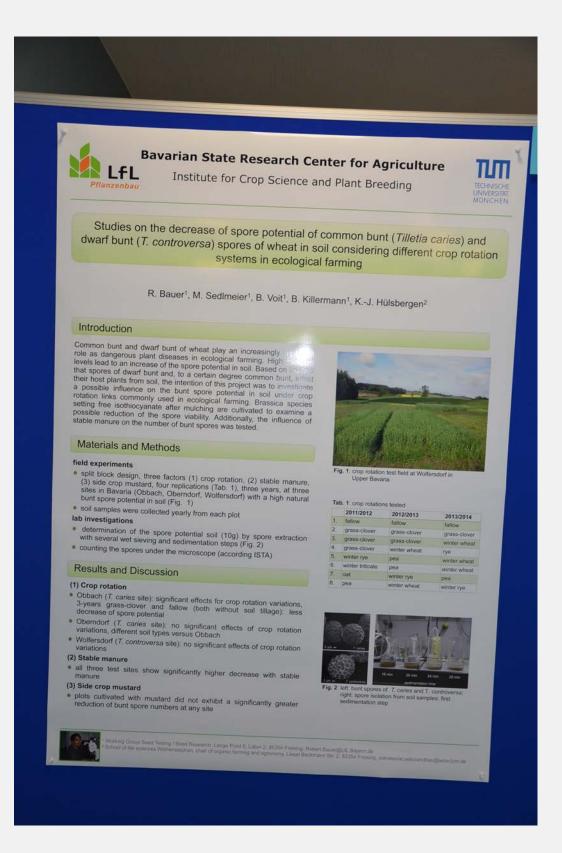
Abriel M.

Influence of tail docking, housing conditions and stocking density on the appearance of cannibalism in weaning piglets



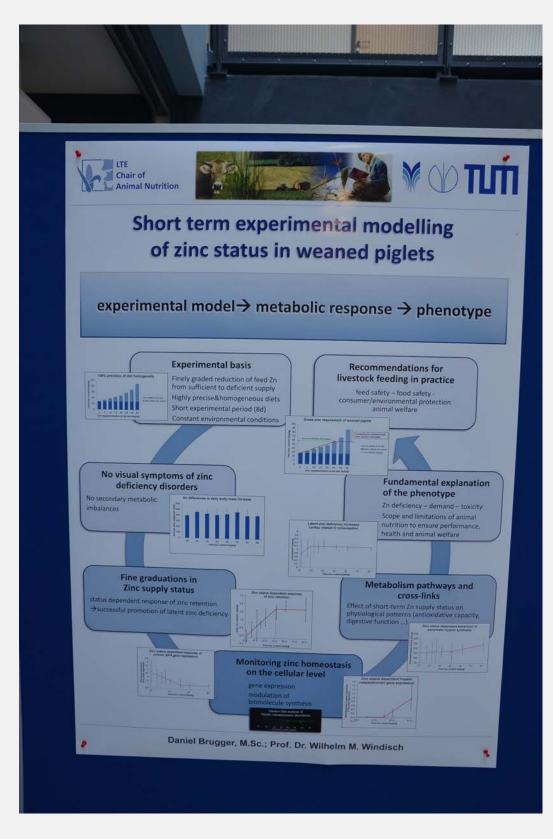
Alpmann J.

Dairy Conflict and resulting association structures: Economic and emotional effects of market liberalization

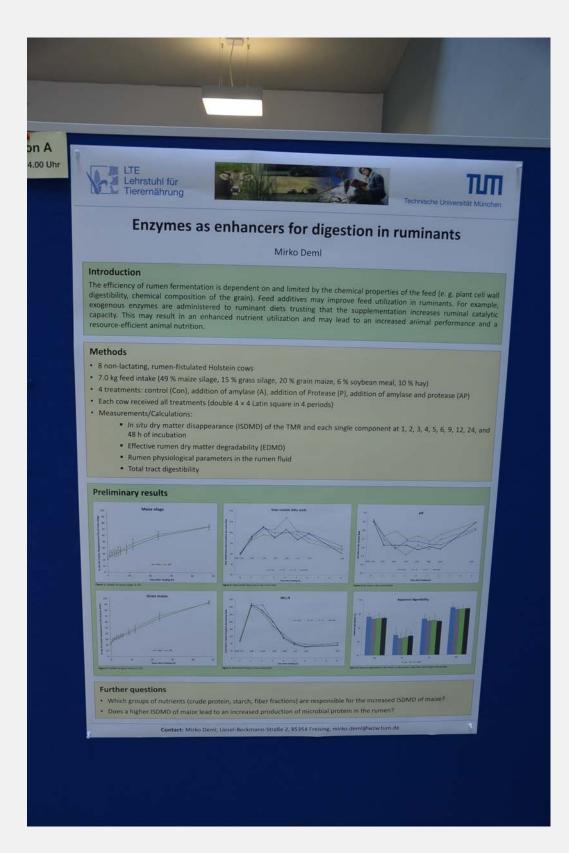


Bauer R.

Studies on the decrease of spore potential of common bunt (Tilletia caries) and dwarf bunt (T. controversa) spores of wheat in soil considering different crop rotation systems in ecological farming



Brugger D. Short term experimental modelling of zinc status in weaned piglets



Deml M. *Enzymes as enhancers for digestion in ruminants*

TUM School of life sciences Weihenstephan

ТШ Nitrogen fluxes of agricultural farming systems

Analysis in an area with high livestock density

Results

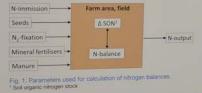
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Felix Forster, Kurt-Jürgen Hülsbergen Chair of organic farming and agronomy, Technical University of Munich, School of life sciences Wehenstephan, Freising E-Mail: *felix.forster@mytum.de*

In the districts Hohenthiann, Pfeffenhausen and Rottenburg a.d. Laaber, a big increase in livestock density took place in the past 10 years. In particular pig farming was expanded, accompanied by an increase in the nitrogen content in groundwater. Therefore a research project was started to analyse nitrogen fluxes and potential nitrogen leaching from arms in this region. As a second step, mitigation strategies will be developed and evaluated.

Methods

- Analysis was conducted with the REPRO model (1)
 Nitrogen balances were calculated on the level of the whole farm, crop types and fields
 Input parameters are displayed in figure 1
 Up to now 5 farms have been analysed (tab. 1)



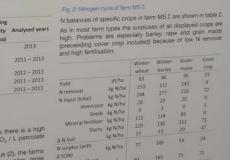
Farm	Farm type	Farm size (ha)	Stocking density (GV/ha)	Analysed years
	Fattening pigs	62	6,0	2013
MS 1	Fattening pigs	69	2,2	2011 - 2013
MS 2	+ Biogas	98	1,8	2012 - 2013
MV1	Dairy Cows	92	0	2011-2013
MF 1	Arable	75	0	2011-2013
845.3	Arable, slurry application			

Tab. 1: Key figures of examined farms

With actual N surpluses of the analysed farms there is a high risk of exceeding the critical level of 50 mg $\rm NO_3$ / L percolate

In order to reach the target of 0-50 kg N surplus (2), the farms, in order to reach their refilization levels. This implies more need to reduce their refilization levels. This implies more inflicient use of slurry nitrogen, as well as a reduction in interal fertilization. Lower N-balances can then be achieved without any or with only a minor reduction in yields.

Literature (1) Kustermann, B., Christen, O., Huisbergen, K.-J. (2010) M. Apriculture, Ecosystems & Environment 135; pp 70–80 Apriculture, Ecosystems & Environment 135; pp 70–80 April 20 DLG (2013) Nachhattger Ackerbau – DLG Merkhatt 389



kg N/ha

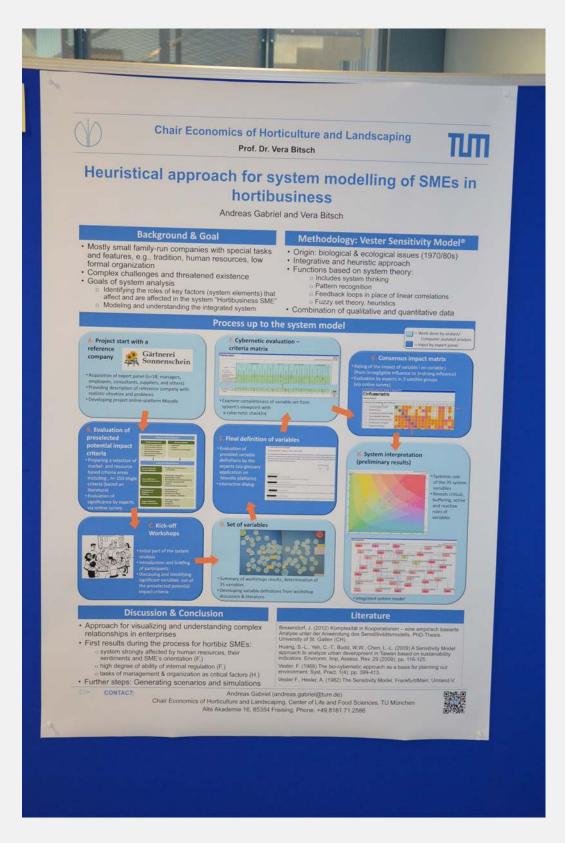
165 41 ke N/ha

S.F.

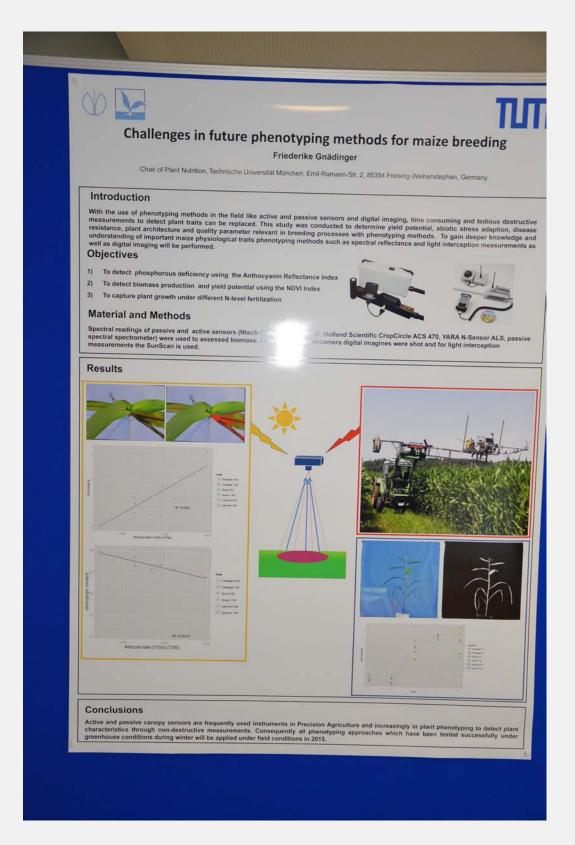
Figure 2 shows the on-farm nitrogen cycle of farm MS 2. In all studied farms N surpluses ranged from 71 to 163 kg N/ha.

Forster F.

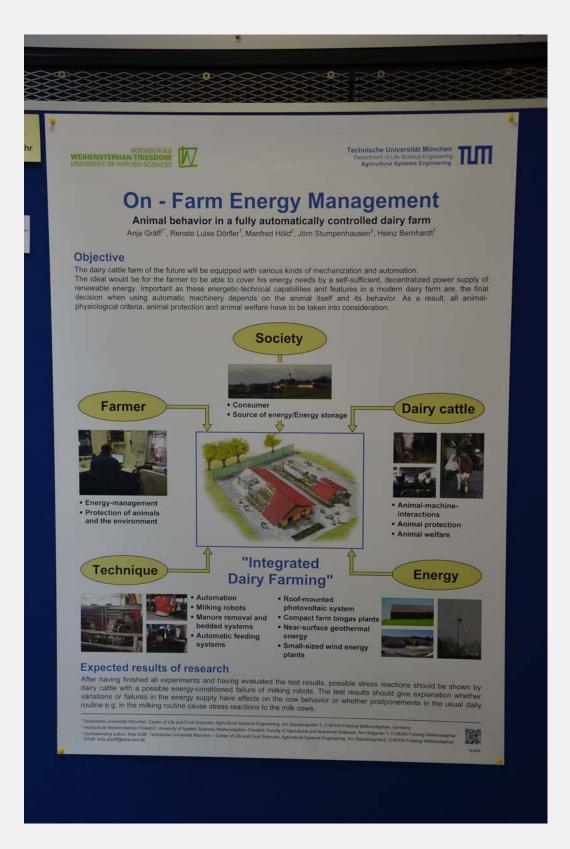
Nitrogen fluxes and potential nitrogen leaching of agricultural farming systems in an area with high livestock density



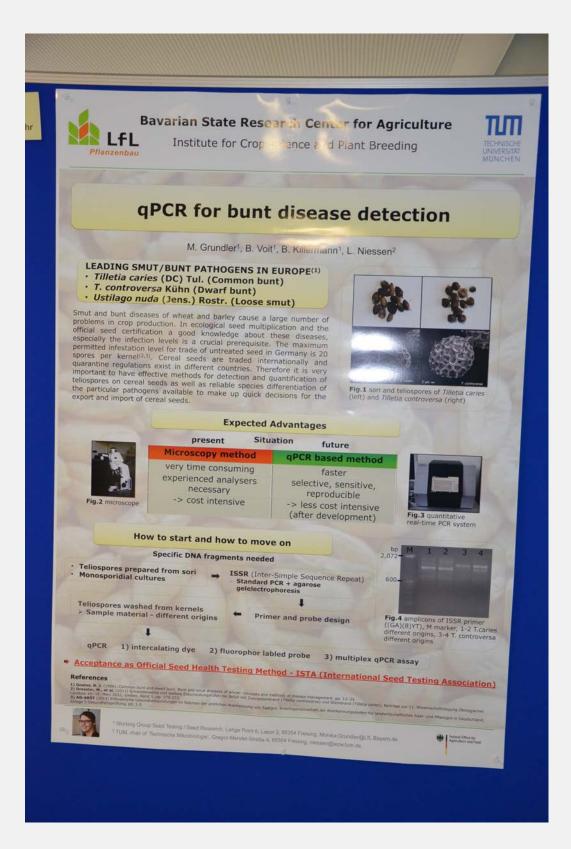
Gabriel A. *Heuristical approach for a system description of SMEs in hortibusiness*



Gnädinger F. *Challenges in future phenotyping methods for maize breeding*

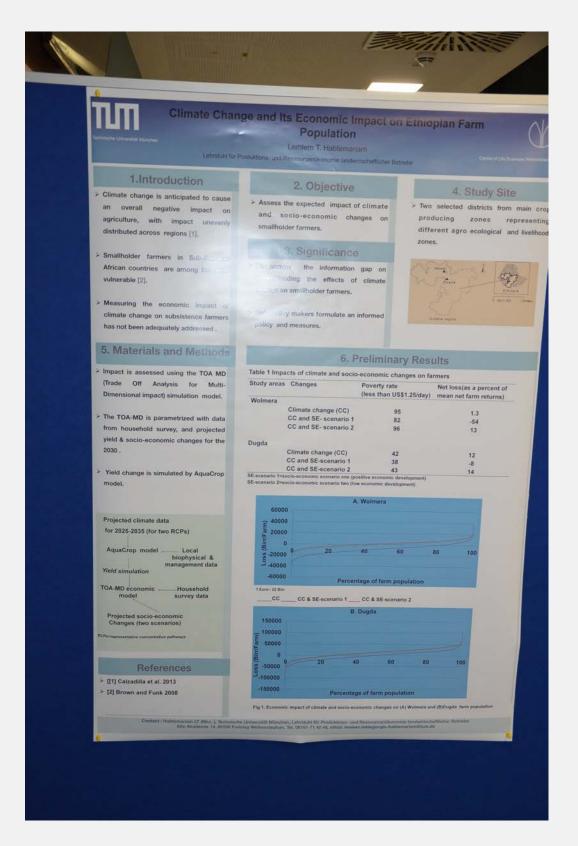


Gräff A. Animal behavior in a fully automatically controlled dairy farm



Grundler M.

Development of quantitative and qualitative test methods for detection of wheat and barley bunt diseases (Tilletia spp., Ustilago nuda) by means of Real-Time PCR assays



Habtemariam L.H. Climate change and its impact on Thiopian Agriculture

Effective vole control in the grassland of Bavaria

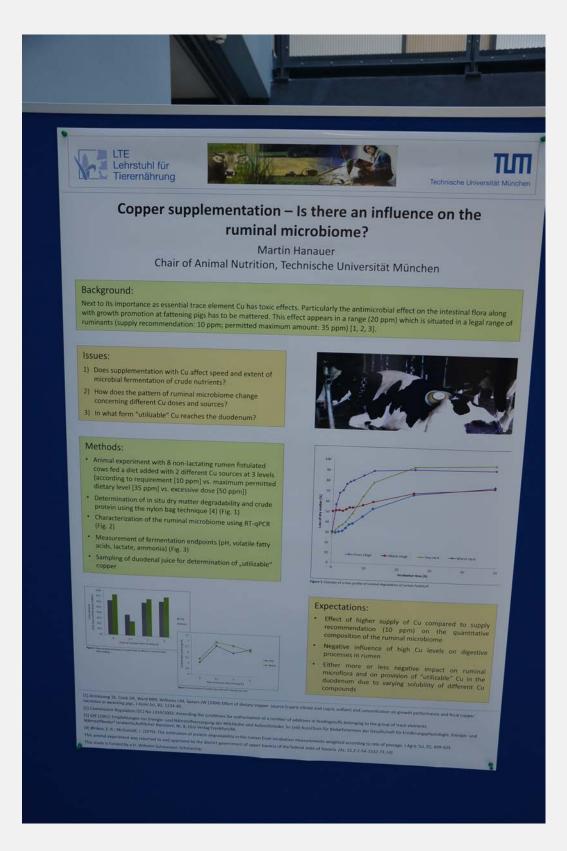
n A

.00 Uhr

Barbara Hailer, IPS 2d

Evildoers Water vole (Arvicola terrestris) Common vole (Microtus arvalis) 120-190 mm Length 80-120 mm 120-190 mm Weight 18-40 g 120-190 g Weight 18-40 g 120-190 mm Length 18-40 g 120-190 mm Weight 18-40 g 120-190 mm Veight 18-40 g 18-40 g Nonitoring or the water vole, colour Dark-grey, brown, never ref-brown 2 month Puberty 11 days 4-5 per year, each with 2-8 Litter 4-7 per year, each with 3-7 young voles Voung voles Project aims 190 days aria 2 month Puberty 11 days aria grassland of Bavaria 2 monthor	77
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Results and Conclusion	ring
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Barbaro Haller, Manfred Sohmen, Dr. Uhren Beine, Bavarian State Research Center for Agriculture, Institute for Paint Protection Institute for Paint Protection Lange Point 10, 85354 Pretsing, www.ffl.bayern.de	

Hailer B. *Effective vole control in the grassland of Bavaria*

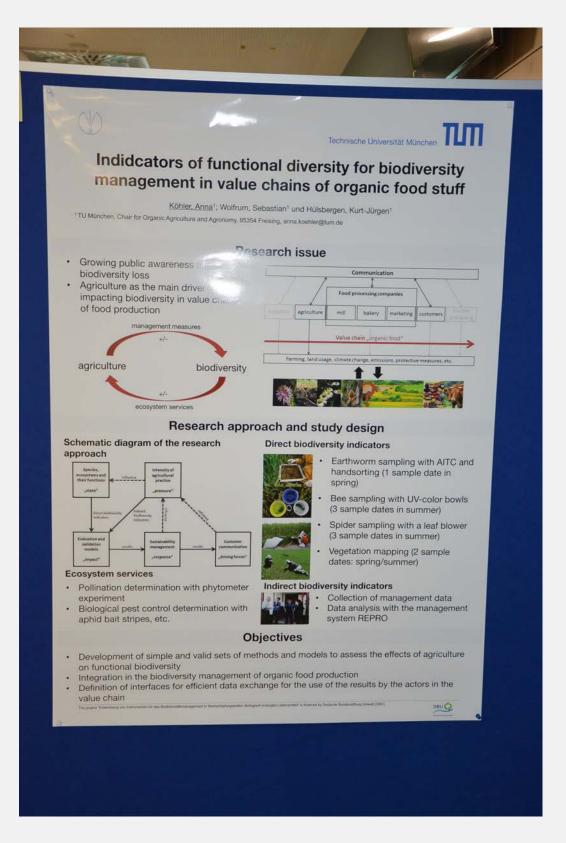


Hanauer M. *Copper supplementation – Is there an influence on the ruminal microbiome?*



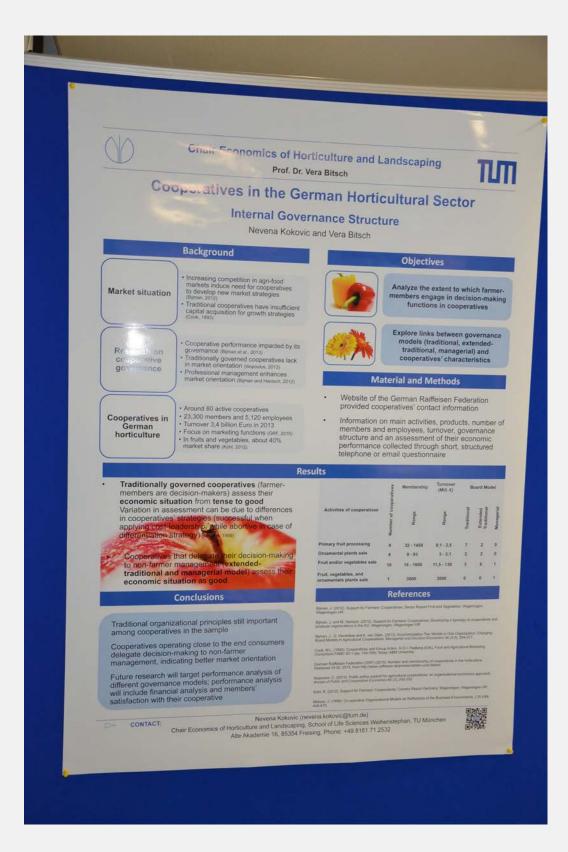
Höld M.

Elaborate the basics for implementation of an on-farm energy management system in a dairy barn



Köhler A.S.

Indicators of functional diversity for biodiversity management in value chains of organic food stuff



Kokovic N.

Cooperatives in the German Horticultural Sector: Internal Governance Structure



Loibl P.

Influence of stressful situations on feed intake behavior in fattening pigs

Lehrstuhl für Geoinformatik

LandModel: A Semantic 3D + t Data Model for Applications in Agricultural Sciences

ТЛП

3D + t Geodatab

ntegration platform for comple-

Estimation of transporation

flows and traffic load caused by

agricultural transport processes

Thomas Machl, Andreas Donaubauer und Thomas H. Kolbe

Core Concept: Coupling of Semantic Data Model and Complex Analytical Methods

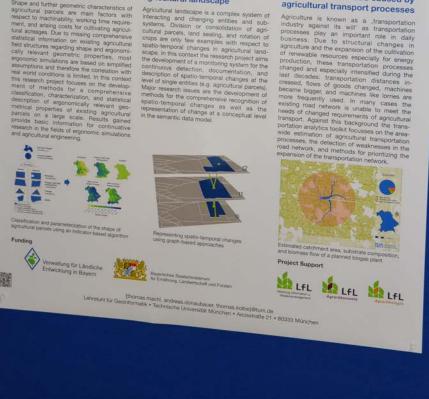
Core Concept: Coupling of Semantic Data Model and Complex Analytic With its research on _3D-Spatio-Temporal Semantic Data Modelling of Agricultural Landscape*, the Geoinformatics group at TUM focusses on the development of a monitoring system for a profound and comprehensive analysis of agricultural landscape. The core of this system is a semantic spatio-temporal data model representing agricultural landscape as a system of changing and interacting entries in three dimensional space. Due to the clear definition of all relevant object classes, attributes, associations, the explicit modeling of spatio-temporal changes at the level of single entries, the conformity with standards of the ISO 19100 series, and the possibility of an application-specific extension, the data model acts as a formally described and machine-interpretable, and interdiacipling integration platform for the development of complex analytical methods. Based on the semantic data model, various tools have been developed, analyting different aspects of agricultural landscape. Currently the land analytics tools in field, tools for a parametric description of the shape of agricultural parcels, tools for estimating tracks in field, tools for the estimation of transport processes as well as tools for the detection of spatio-temporal-temporal changes of agricultural parcels. All information gained throughout the analysis processes is used for semantic encomment of corresponding entities in the 3D + 1 geodatabase and is therefore available for further analysis at the level of angle entities. As special emphasis is put on the scalability of the tools, large areas can be analyzed on a large scale (e.g. all agricultural parcels in the entities in the obsel agricultural parcels in the entities of angle models in the tools in the entities in the entities in the entities and agricultural parcels in the entity of Bavaria). Parametric description of the

Parametric description of the shape of agricultural parcels

Im an ergonomic point of view peak during geometric characteristics of cultural parcels are main factors with pact or machinability, working inter equire-tation of the second second second second is accessed on the second second second accessed on the second second second stateal internation on existing agricultural distructions are based regronomic provide second second second second accessed project focuses on the develop-reveal properties of existing agricultural social properties of existing agricultural social properties of existing agricultural social of for a comprehensive social of the second second second second second of the second second second second of the second second second second second of the second second second second second of the second second second second second to the second second second second second to the second second second second to the second second second second second second to the second s

Detection and analysis of spatio-temporal changes in from an ergonomic point of view agricultural landscape

Agricultural landscape Agricultural indicape is a complex system of interacting and changing entities and sub-systems. Division or consolidation of agri-cultural parcels, land sealing, and rotation of crops are only fee vasimes with respect to spatio-temporal changes in agricultural land-scape. In this content the agricultural langes and the development of a monitoring system for the continuous detection, documentation, and description of spatio-temporal changes at the level of angle entities (e.g. agricultural parcels). Major research issues are the development of mathod sentises (e.g. agricultural parcels) mathod the complementies recognition of mathod sentises of changes at a conceptual level in the semantic data model.



Machl T.

3D-Spatio-Temporal Semantic Data Modelling for Applications in the Agricultural Sciences



Technische Universität München Department of Life Science Engineering Agricultural Systems Engineering

Analysis of Influencing Factors on Infield-Logistics

Michael Mederle, Heinz Bernhardt

Abstract:

Agricultural logistics extremely increased in the last years. For process optimization several software tools have been developed to navigate vehicles to the fields. Regarding infield-logistics and navigation in the fields only first steps have been made. The main question is the systematics of doing the field work and the corresponding influencing factors. In contrast to road navigation infield-logistics is understood as area navigation. An endless number of tracks are selectable but only few are realistic. Common strategies of different farmers should be investigated and analyzed in terms of efficiency, process- and down-times.

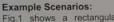


Fig.1 shows a rectangular field. Scenario A represents tillage operations. Neither supply- nor removal-logistics is needed. Usually these operations are done in long tracks for minimizing turning times. Scenario B and C show the application of liquid manure. The field roads affect the infield-logistics because the operating vehicle has to leave the field periodically for refilling. Infield-logistics for slurry application also depends on factors like application amount, working width or tank volume. Scenario B differs from C regarding tramline distances. In B this distance is less, so the whole field length can be working width or tank volume. In the field, and worked and no more turnings in the field are necessary.

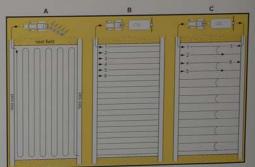
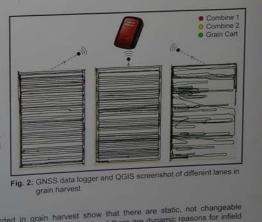


Fig. 1: Different infield-strategies depending on various operations

Material and Methods: The investigation consists of two different parts. First there will be an interrogation of farmers about the reasons and influences for their infield strategies in terms of an expert interview. Furthermore different driving lanes will be recorded by GNSS data loggers (Fig. 2) for analyzing the operations regarding efficiency, process- and down-times. The data acquisition will include all production steps from tillage to harvest. Additionally it will take place all over Germany to be able to represent different agricultural landscapes with different preconditions.



Expected results: First results of the GNSS tracks analysis recorded in grain harvest show that there are static, not changeable influencing factors like field shape, field size or field entries. On the other hand there are dynamic reasons for infled strategies which are changeable, e.g. weather conditions, different varieties or various driver skills. These trends should be checked by the interrogation and further GNSS data recordings. Prof. Dr. Heinz Bernhardt E-Mail: heinz bernhardt@wzw.tum de Letzelugt für Amerikanischer State D M.Sc. Michael Mederle, 2015 E-Mail: michael mederle@wzw.tum.de

Mederle M.

Analysis of Influencing Factors on Infield-Logistic



TECHNOLOGIEZENTRUM ENERGIE



Cryogenic removal of carbon dioxide from variable CH₄/CO₂ gas mixtures, Liquefied biomethane (LBM) from biogas for long-term energy storage Department of Life Science Engineering, Agricultural Systems Engineering, GZW, UAS Landshut, Faculty mechanical engineering

Abstract:



Nachtmann K.

Development of a laboratory plant to produce liquefied biomethane and dry ice from biogas



Oliveira V.C. Soil functionality indicators and multifunction assessment of Cerrado – Brazil



Rombach M. A typology of online flower shops on the German market

Bavarian State Research Center for Agriculture TECHNISCHE UNIVERSITA Institute for Agricultural Engineering and Animal Husbandry Technische Universität Dresden Tier und Technik -51 Chair of Agricultural Systems and Technology Seeder Mobile platform Laserscanner Mulcher Background Pasture care is an important factor in pasture management. Quantity and quality losses of pasture forage are consequences of insufficient pasture care. An optimal pasture care includes selective mulching of weeds and seeding on areas without vegetation. Until now these operations have been done manually, extensive by machine or there was no pasture care at all. Selective improvement of pasture conditions after grazing increases the potential of pasturing. Objective Results Autonomous mobile machine for selective pasture care: • Ensuring stable and reliable movement under real > Analysis of constraints for the operating process pasture conditions > Detection of soil profiles on pastures Localization of pasture spots for maintenance operations E and the N Performance of maintenance tasks on pasture J.L 19 1 **Material and Methods** x [m] x Design based on a evaluated and selected existing remote-controlled platform Sensor carriage (at left); soil profile (at right) Evaluation and selection of sensors for localization of Evaluation of mulcher types pasture spots for maintenance operations Equipping with selected sensors and Definition of Analysis of actuators (mulcher and seeder) requirements existing technique Development of the low level vehicle control Technical implementation of the interaction of Selection of technique sensors and actuators **Conclusion and Outlook** Next step is the technical implementation: Equipping the acquired platform with sensors Equipping with attachments Development of the low level control for Remote-controlled machine as a platform for autonomous operation the pasture robot (at left); flail mulcher (at right) Tests of sensors to detect pasture data for calibration and checking the reliability under pasture conditions. Institute for Agricultural Engineering and Animal Husbandry, Am Staudengarten 3, 85354 Freising Tel: +49-6161-71-3097, E-Mail: Benjamin Seiferth@Lft. bayern.de, Internet. http://www.Lft.bayern.de/it/

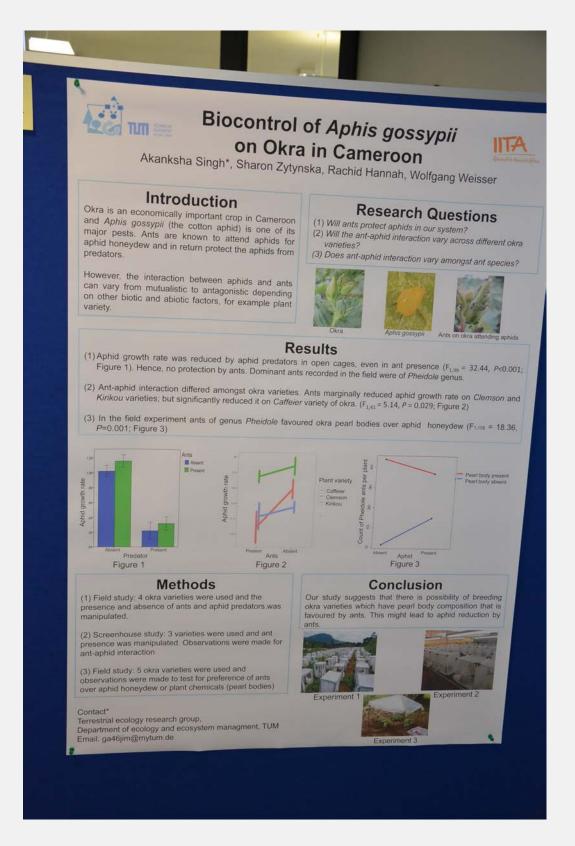
Seiferth B.

Development of a system for selective machining on pasture to automate pasture care by an autonomous mobile robot

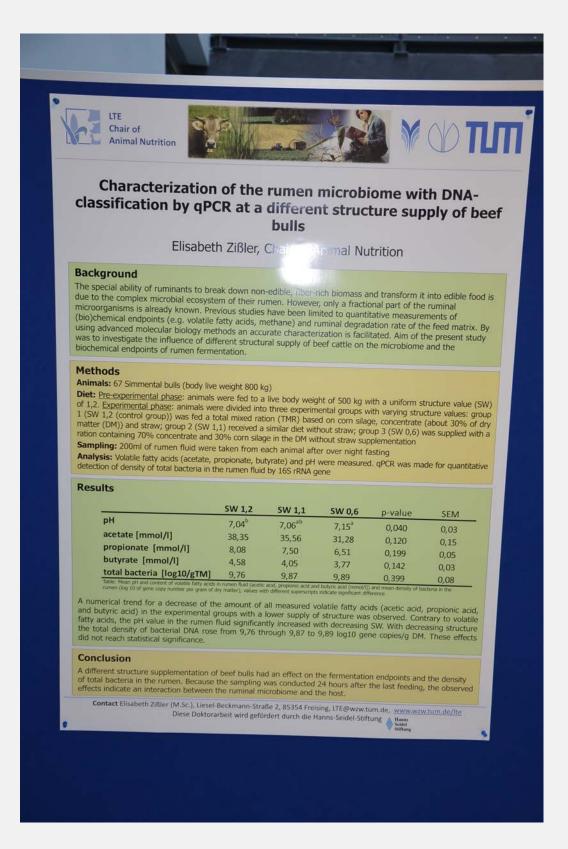


Sghyer H.

Investigating the genetic structure and diversity of the barley pathogen Ramularia collocygni



Singh A. Biocontrol of Aphis gossypii on okra in Cameroon



Zißler E.

Characterization of the rumen microbiome with DNA-classification by qPCR at a different structure supply of beef bulls